

Fixed-Point Property on Triod-like Continua

Paul Gooderham-Belanger
(pjgooderhambelanger557@community.nipissingu.ca)

Nipissing University

May 28, 2015

History

Question (Bing 1969)

Does each tree-like continuum have the fixed-point property?

History

Question (Bing 1969)

Does each tree-like continuum have the fixed-point property?

Answered in the negative by D. P. Bellamy in 1979

History

Question (Bing 1969)

Does each tree-like continuum have the fixed-point property?

Answered in the negative by D. P. Bellamy in 1979

Question (Hagopian 2007)

Does every triod-like continuum have the fixed-point property?

History

Question (Bing 1969)

Does each tree-like continuum have the fixed-point property?

Answered in the negative by D. P. Bellamy in 1979

Question (Hagopian 2007)

Does every triod-like continuum have the fixed-point property?

Question (Hagopian 2007)

Do there exist two commuting maps of a triod onto itself that do not have a coincidence point?

History

Question (Bing 1969)

Does each tree-like continuum have the fixed-point property?

Answered in the negative by D. P. Bellamy in 1979

Question (Hagopian 2007)

Does every triod-like continuum have the fixed-point property?

Question (Hagopian 2007)

Do there exist two commuting maps of a triod onto itself that do not have a coincidence point?

Confirming Question 3 would provide a counter-example for Question 2.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Let S be the inverse limit of triods under the bonding maps $f_i = f$. Then $S = \varprojlim(T, f) = \{p = (p_1, p_2, \dots) : p_i \in T \text{ and } f(p_{i+1}) = p_i \forall i\}$.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Let S be the inverse limit of triods under the bonding maps $f_i = f$. Then $S = \varprojlim(T, f) = \{p = (p_1, p_2, \dots) : p_i \in T \text{ and } f(p_{i+1}) = p_i \forall i\}$.

Let $\tilde{g} : S \rightarrow S$ be such that $\tilde{g}(p) = (g(p_2), g(p_3), \dots) \forall p \in S$.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Let S be the inverse limit of triods under the bonding maps $f_i = f$. Then $S = \varprojlim(T, f) = \{p = (p_1, p_2, \dots) : p_i \in T \text{ and } f(p_{i+1}) = p_i \forall i\}$.

Let $\tilde{g} : S \rightarrow S$ be such that $\tilde{g}(p) = (g(p_2), g(p_3), \dots) \forall p \in S$.

Note that $\tilde{g}(p) \in S$ since $f(g(p_{i+1})) = g(f(p_{i+1})) = g(p_i)$.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Let S be the inverse limit of triods under the bonding maps $f_i = f$. Then $S = \varprojlim(T, f) = \{p = (p_1, p_2, \dots) : p_i \in T \text{ and } f(p_{i+1}) = p_i \forall i\}$.

Let $\tilde{g} : S \rightarrow S$ be such that $\tilde{g}(p) = (g(p_2), g(p_3), \dots) \forall p \in S$.

Note that $\tilde{g}(p) \in S$ since $f(g(p_{i+1})) = g(f(p_{i+1})) = g(p_i)$.

Now suppose that \tilde{g} has a fixed point. Then for some $p \in S$ we have $\tilde{g}(p) = p \Rightarrow (g(p_2), g(p_3), \dots) = (p_1, p_2, \dots) \Rightarrow g(p_2) = p_1$.

Proposition

Let f and g be two continuous maps of a triod onto itself. If f and g are disjoint and commuting, then there exists a triod-like continuum which does not have the fixed-point property.

Proof.

Let f and g be two continuous disjoint commuting maps of a triod T onto itself.

Let S be the inverse limit of triods under the bonding maps $f_i = f$. Then $S = \varprojlim(T, f) = \{p = (p_1, p_2, \dots) : p_i \in T \text{ and } f(p_{i+1}) = p_i \forall i\}$.

Let $\tilde{g} : S \rightarrow S$ be such that $\tilde{g}(p) = (g(p_2), g(p_3), \dots) \forall p \in S$.

Note that $\tilde{g}(p) \in S$ since $f(g(p_{i+1})) = g(f(p_{i+1})) = g(p_i)$.

Now suppose that \tilde{g} has a fixed point. Then for some $p \in S$ we have $\tilde{g}(p) = p \Rightarrow (g(p_2), g(p_3), \dots) = (p_1, p_2, \dots) \Rightarrow g(p_2) = p_1$.

But f and g are disjoint and we have $f(p_2) = p_1 = g(p_2)$. This is a contradiction. Thus \tilde{g} does not contain a fixed point.



Data Structure

- $T = \{(i, d) : i \in \{0, 1, 2\}, d \in [0, 1]\}$

Data Structure

- $T = \{(i, d) : i \in \{0, 1, 2\}, d \in [0, 1]\}$
- A triod is represented as a series of connected vertices

Data Structure

- $T = \{(i, d) : i \in \{0, 1, 2\}, d \in [0, 1]\}$
- A triod is represented as a series of connected vertices
- Given $N, M \in \mathbb{N}$, a mapping $f : T_N \rightarrow T_M$ maps a triod with $3N + 1$ vertices onto a triod with $3M + 1$ vertices.

Data Structure

- $T = \{(i, d) : i \in \{0, 1, 2\}, d \in [0, 1]\}$
- A triod is represented as a series of connected vertices
- Given $N, M \in \mathbb{N}$, a mapping $f : T_N \rightarrow T_M$ maps a triod with $3N + 1$ vertices onto a triod with $3M + 1$ vertices.
- Points on triod are interpolated between vertices

Data Structure

- $T = \{(i, d) : i \in \{0, 1, 2\}, d \in [0, 1]\}$
- A triod is represented as a series of connected vertices
- Given $N, M \in \mathbb{N}$, a mapping $f : T_N \rightarrow T_M$ maps a triod with $3N + 1$ vertices onto a triod with $3M + 1$ vertices.
- Points on triod are interpolated between vertices
- Interpolation enforces continuity of resultant maps.

Generating Mappings

Generating Mappings

- Every mapping starts with the image of the branch point

Generating Mappings

- Every mapping starts with the image of the branch point
- Let N be the number of vertices per leg of the domain triod
- The for each leg i , take $f(i, \frac{d+1}{N})$ such that it is adjacent to $f(i, \frac{d}{N})$.

Generating Mappings

- Every mapping starts with the image of the branch point
- Let N be the number of vertices per leg of the domain triod
- The for each leg i , take $f(i, \frac{d+1}{N})$ such that it is adjacent to $f(i, \frac{d}{N})$.
- Recursively permute over every combination

The search space grows very quickly!

The search space grows very quickly!

M \ N	1	2	3	4	5
1	88	1648	34 240	694 528	14 182 912
2	X	4759	313 281	3 572 647	96 722 809
3	X	X	211 972	6 295 732	186 132 664
4	X	X	X	8 307 175	252 055 519
5	X	X	X	X	302 795 176

The search space grows very quickly!

M \ N	1	2	3	4	5
1	88	1648	34 240	694 528	14 182 912
2	X	4759	313 281	3 572 647	96 722 809
3	X	X	211 972	6 295 732	186 132 664
4	X	X	X	8 307 175	252 055 519
5	X	X	X	X	302 795 176

Remember that we need to check each of these pair-wise with each other. Thus for $N=4$, $M=2$, we need to check $\binom{3572647}{2} = 6.38 \times 10^{12}$ pairs!

High Performance Computing to the Rescue

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout
- Master program generates pairs of empty mappings specifying only the image of the base point

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout
- Master program generates pairs of empty mappings specifying only the image of the base point
- Master program distributes pairs to worker programs

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout
- Master program generates pairs of empty mappings specifying only the image of the base point
- Master program distributes pairs to worker programs
- Worker programs generate all completions and check for commutativity and disjointness.

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout
- Master program generates pairs of empty mappings specifying only the image of the base point
- Master program distributes pairs to worker programs
- Worker programs generate all completions and check for commutativity and disjointness.
- Worker programs report winning pairs back to master program

High Performance Computing to the Rescue

- Can utilize hundreds of CPU Cores at once to speed up the process.
- Program was implemented on the SHARCNET Compute cluster in Python over MPI
- Program uses a master/slave layout
- Master program generates pairs of empty mappings specifying only the image of the base point
- Master program distributes pairs to worker programs
- Worker programs generate all completions and check for commutativity and disjointness.
- Worker programs report winning pairs back to master program
- Master program records winning mappings for further investigation

Checking Disjointness

Checking Disjointness

$\forall i \in \{0, 1, 2\}$:
 $\forall \text{ vertex } \frac{d}{N}$:

Checking Disjointness

$\forall i \in \{0, 1, 2\}$:

\forall vertex $\frac{d}{N}$:

If $f(i, \frac{d}{N}) = g(i, \frac{d}{N})$ then we have co-incidence at the vertex.

Checking Disjointness

$\forall i \in \{0, 1, 2\}$:

\forall vertex $\frac{d}{N}$:

If $f(i, \frac{d}{N}) = g(i, \frac{d}{N})$ then we have co-incidence at the vertex.

If $f(i, \frac{d}{N}) = g(i, \frac{d+1}{N})$ and $f(i, \frac{d+1}{N}) = g(i, \frac{d}{N})$ then we have co-incidence between vertices.

Checking Disjointness

$\forall i \in \{0, 1, 2\}$:

\forall vertex $\frac{d}{N}$:

If $f(i, \frac{d}{N}) = g(i, \frac{d}{N})$ then we have co-incidence at the vertex.

If $f(i, \frac{d}{N}) = g(i, \frac{d+1}{N})$ and $f(i, \frac{d+1}{N}) = g(i, \frac{d}{N})$ then we have co-incidence between vertices.

Otherwise the maps are disjoint.

Checking Commutativity

Checking Commutativity

- Define distance using a railway metric

Checking Commutativity

- Define distance using a railway metric

Choose a small $\epsilon > 0$. Choose a large $D \in \mathbb{N}$

Checking Commutativity

- Define distance using a railway metric

Choose a small $\epsilon > 0$. Choose a large $D \in \mathbb{N}$

Let $d = \max_{v \in \{0,1,2,\dots,D\}} \{|(f \circ g)(i, \frac{v}{D}) - (g \circ f)(i, \frac{v}{D})|\}$.

Checking Commutativity

- Define distance using a railway metric

Choose a small $\epsilon > 0$. Choose a large $D \in \mathbb{N}$

Let $d = \max_{v \in \{0,1,2,\dots,D\}} \{|(f \circ g)(i, \frac{v}{D}) - (g \circ f)(i, \frac{v}{D})|\}$.

If $d < \epsilon$ then the maps commute.

Reducing the Search Space

Reducing the Search Space

- Enforcing Disjointness

Reducing the Search Space

- Enforcing Disjointness
- Surjectivity

Enforcing Disjointness

Enforcing Disjointness

- After generating the first map, generate the second map based on it
- skip completions which would cause a co-incidence condition

Surjectivity

Surjectivity

- We can enforce that each map is surjective

Surjectivity

- We can enforce that each map is surjective
- The vast majority of maps are not surjective

Surjectivity

- We can enforce that each map is surjective
- The vast majority of maps are not surjective
- **eg:** With $N=5$, $M=3$ we have 186 132 664 maps.

Surjectivity

- We can enforce that each map is surjective
- The vast majority of maps are not surjective
- **eg:** With $N=5$, $M=3$ we have 186 132 664 maps.
- Only 86 094 are surjective.

Results so far

Results so far

- Ran up to $N=4$, $M=2$ without surjective generation

Results so far

- Ran up to $N=4$, $M=2$ without surjective generation
- No Maps found yet

Results so far

- Ran up to $N=4$, $M=2$ without surjective generation
- No Maps found yet

Thank you.

<https://github.com/Nomadluap/TriodEnumeration>