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δ -SEMIOPEN SETS IN TOPOLOGY

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ABSTRACT. It is the object of this paper to study further the notion of δ - Λ_s -semiclosed sets which is defined as the intersection of a δ - Λ_s -set and a δ -semiclosed set. Moreover, we introduce some low separation axioms using the above notions. Also, we present and study the notions of δ - Λ_s -continuous functions, Λ_s -compact spaces and δ - Λ_s -connected spaces.

1. INTRODUCTION

In 1963, N. Levine [2] offered a new notion in the field of topology by introducing the notion of semi-open sets. He defined this new class of sets by using the known concept of the closure of an open set, i.e. a subset A of a space X is *semi-open* if it is a subset of the closure of its interior. This new class of sets properly contains the class of all open sets. Since the advent of the notion of semi-open sets, several other generalized open sets came to existence, such as preopen sets [[4], [10]], α -open sets [11], β -open sets [[1], [2]], δ -open sets [5] and etc. The study of topological properties via these generalized open sets has gained significant importance in General Topology and its applications (see for example [6], [7], [5]).

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In what follows (X, τ) and (Y, σ) (or X and Y) are topological spaces and A is a subset of X . By $Int(A)$ and $Cl(A)$ we denote the interior and the closure of A , respectively. In 1968, N. V. Velićko [5] introduced the notion of δ -open sets in order to investigate the characterization of H -closed spaces, i.e. a Hausdorff space is H -closed if its image is closed in every Hausdorff space in which it can be embedded. The δ -interior of a subset A of a space (X, τ) , denoted by $Int_\delta(A)$, is the union of all regular open sets of (X, τ) contained in A . Recall that a subset A of X is called *regular open* if $A = Int(Cl(A))$. A subset A of a space (X, τ) is δ -open if $A = Int_\delta(A)$. This means that a set is δ -open if it is the union of regular open sets. The complement of a δ -open set is called δ -closed. Alternatively, a subset A of a space (X, τ) is called δ -closed if $A = Cl_\delta(A)$, where $Cl_\delta(A) = \{x \in X \mid Int(Cl(U)) \cap A \neq \emptyset, U \in \tau \text{ and } x \in U\}$. It is worth to be noticed that the family of all δ -open sets form a topology on X . Moreover, the notion of δ -open sets found its way in digital topology in what it is called the Khalimsky line or the so-called digital line (see [7]). Such line is the set \mathcal{Z} of integers equipped with the topology \mathcal{K} having $\{\{2n-1, 2n, 2n+1\} \mid n \in \mathcal{Z}\}$ as a subbase. This kind of space is of great importance in the study of applications of point-set topology to computer graphics.

A subset A of (X, τ) is said to be δ -semiopen set [12] if there exists a δ -open set U of X such that $U \subset A \subset Cl(U)$. The complement of a δ -semiopen set is called a δ -semiclosed set. A point $x \in X$ is called the δ -semicluster point of A if $A \cap U \neq \emptyset$ for every δ -semiopen set U of X containing x . The set of all δ -semicluster points of A is called the δ -semiclosure of A , denoted by $sCl_\delta(A)$. We denote the collection of all δ -semiopen (resp. δ -semiclosed) sets by $\delta SO(X, \tau)$ (resp. $\delta SC(X, \tau)$). We say that a subset U of X is a δ -semineighborhood of a point $x \in X$ if U contains a δ -semiopen set to which x belongs.

Lemma 1.1. (see [3]) *The following statements are true:*

- (1) *Intersection of arbitrary collection of δ -semiclosed sets in (X, τ) is δ -semiclosed*
- (2) *Let A be a subset of a space (X, τ) . Then*

$$sCl_\delta(A) = \cap \{F \in \delta SC(X, \tau) \mid A \subset F\}.$$

- (3) *$sCl_\delta(A)$ is δ -semiclosed, that is $sCl_\delta(sCl_\delta(A)) = sCl_\delta(A)$.*

Lemma 1.2. (see [3]) For subsets A and A_i ($i \in I$) of a space X , the following hold:

- (1) $A \subset sCl_\delta(A)$.
- (2) If $A \subset B$, then $sCl_\delta(A) \subset sCl_\delta(B)$.
- (3) $sCl_\delta(\cap\{A_i : i \in I\}) \subset \cap\{sCl_\delta(A_i) : i \in I\}$.
- (4) $sCl_\delta(\cup\{A_i : i \in I\}) = \cup\{sCl_\delta(A_i) : i \in I\}$.
- (5) A is δ -semiclosed if and only if $A = sCl_\delta(A)$.

2. Λ_δ^s -SETS

Definition 1. Let A be a subset of a space X . By $\Lambda_\delta^s(A)$ we denote the set

$$\cap\{O \in \delta SO(X, \tau) : A \subset O\}.$$

The subset A of X is called Λ_δ^s -set if $A = \Lambda_\delta^s(A)$.

Lemma 2.1. For subsets A and A_i ($i \in I$) of a space X , the following hold:

- (1) $A \subset \Lambda_\delta^s(A)$.
- (2) $\Lambda_\delta^s(\Lambda_\delta^s(A)) = \Lambda_\delta^s(A)$.
- (3) If $A \subset B$, then $\Lambda_\delta^s(A) \subset \Lambda_\delta^s(B)$.
- (4) $\Lambda_\delta^s(\cap\{A_i : i \in I\}) \subset \cap\{\Lambda_\delta^s(A_i) : i \in I\}$.
- (5) $\Lambda_\delta^s(\cup\{A_i : i \in I\}) = \cup\{\Lambda_\delta^s(A_i) : i \in I\}$.
- (6) $\Lambda_\delta^s(A)$ is a Λ_δ^s -set.
- (7) If A is δ -semiopen, then A is a Λ_δ^s -set.
- (8) If A_i is Λ_δ^s -set for each $i \in I$, then $\cap\{A_i : i \in I\}$ is a Λ_δ^s -set.
- (9) If A_i is Λ_δ^s -set for each $i \in I$, then $\cup\{A_i : i \in I\}$ is a Λ_δ^s -set.

Definition 2. Let A be a subset of a space X . By $\Lambda_\delta^{s*}(A)$ we denote the set

$$\cup\{B \in \delta SC(X, \tau) : B \subset A\}.$$

The subset A of X is called Λ_δ^{s*} -set if $A = \Lambda_\delta^{s*}(A)$.

We obtain the following lemma which is similar to Lemma 2.1.

Lemma 2.2. For subsets A, B and A_i ($i \in I$) of a space X the following properties hold:

- (1) $\Lambda_\delta^{s*}(A) \subseteq A$.
- (2) If $A \subseteq B$, then $\Lambda_\delta^{s*}(A) \subseteq \Lambda_\delta^{s*}(B)$.
- (3) If A is δ -closed, then $\Lambda_\delta^{s*}(A) = A$.
- (4) $\Lambda_\delta^{s*}(\cap\{A_i : i \in I\}) = \cap\{\Lambda_\delta^{s*}(A_i) : i \in I\}$.
- (5) $\cup\{\Lambda_\delta^{s*}(A_i) : i \in I\} \subseteq \Lambda_\delta^{s*}(\cup\{A_i : i \in I\})$.

- (6) $\Lambda_\delta^s(X - A) = X - \Lambda_\delta^{s*}(A)$ and $\Lambda_\delta^{s*}(X - A) = X - \Lambda_\delta^s(A)$.
 (7) $\Lambda_\delta^{s*}(A)$ is a Λ_δ^{s*} -set.
 (8) If A is a δ -closed set, then A is a Λ_δ^{s*} -set.
 (9) If A_i is a Λ_δ^{s*} -set for each $i \in I$, then $\cup\{A_i : i \in I\}$ and $\cap\{A_i : i \in I\}$ are Λ_δ^{s*} -sets.

Proof. We prove only the relations (6) and (7).

(6) We have:

$$\begin{aligned} X - \Lambda_\delta^{s*}(A) &= X - \cup\{B \in \delta SC(X, \tau) : B \subset A\} \\ &= \cap\{B^c \in \delta SO(X, \tau) : A^c \subset B^c\} \\ &= \Lambda_\delta^s(A^c) = \Lambda_\delta^s(X - A) \end{aligned}$$

Similarly, we have: $\Lambda_\delta^{s*}(X - A) = X - \Lambda_\delta^s(A)$.

(7) We have

$$\begin{aligned} \Lambda_\delta^{s*}(\Lambda_\delta^{s*}(A)) &= \Lambda_\delta^{s*}(X - \Lambda_\delta^s(X - A)) \\ &= X - \Lambda_\delta^s(\Lambda_\delta^s(X - A)) \\ &= X - \Lambda_\delta^s(X - A) \\ &= X - (X - \Lambda_\delta^{s*}(A)) = \Lambda_\delta^{s*}(A) \end{aligned}$$

Thus, the set $\Lambda_\delta^{s*}(A)$ is a Λ_δ^{s*} -set. □

Proposition 2.3. Let (X, τ) be a space,

$$\tau^{\Lambda_\delta^s} = \{A : A \text{ is a } \Lambda_\delta^s \text{-set of } X\}$$

and

$$\tau^{\Lambda_\delta^{s*}} = \{A : A \text{ is a } \Lambda_\delta^{s*} \text{-set of } X\}.$$

Then, the pairs $(X, \tau^{\Lambda_\delta^s})$ and $(X, \tau^{\Lambda_\delta^{s*}})$ are Alexandroff spaces.

3. δ - Λ_s -SEMICLOSED SETS

Definition 3. A subset A of a space X is called δ - Λ_s -semiclosed, denoted by $(\Lambda, s\delta)$ -closed, if $A = T \cap C$, where T is a Λ_δ^s -set and C is a δ -semiclosed set.

Example 3.1. ([3], Example 5) Let (X, τ) be a space such that $X = \{a, b, c\}$ and $\tau = \{\emptyset, X, \{a\}, \{b\}, \{a, b\}\}$. Clearly, the family of all δ -open sets is the family τ and

$$\delta SO(X, \tau) = \{\emptyset, X, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, c\}\}.$$

Also, the family of all $(\Lambda, s\delta)$ -closed sets is the family

$$\{\emptyset, X, \{a\}, \{b\}, \{c\}, \{a, b\}, \{b, c\}, \{a, c\}\}.$$

The set $A = \{c\}$ is Λ_δ^s -set and the set $B = \{a, b\}$ is $(\Lambda, s\delta)$ -closed but are not δ -semiopen sets.

Proposition 3.2. *Let A be a subset of a space X . The following conditions are equivalent:*

- (1) A is $(\Lambda, s\delta)$ -closed,
- (2) $A = T \cap sCl_\delta(A)$, where T is a Λ_δ^s -set,
- (3) $A = \Lambda_\delta^s(A) \cap sCl_\delta(A)$.

Proof. (1) \Rightarrow (2): Let $A = T \cap C$, where T is a Λ_δ^s -set and C is a δ -semiclosed set. Since $A \subset C$, we have $sCl_\delta(A) \subset C$ and

$$A = T \cap C \supset T \cap sCl_\delta(A) \supset A.$$

Therefore, we obtain $A = T \cap sCl_\delta(A)$.

(2) \Rightarrow (3): Let $A = T \cap sCl_\delta(A)$, where T is a Λ_δ^s -set. Since $A \subset T$, we have $\Lambda_\delta^s(A) \subset \Lambda_\delta^s(T) = T$ and hence

$$A \subset \Lambda_\delta^s(A) \cap Cl_\delta(A) \subset T \cap sCl_\delta(A) = A.$$

Therefore, we obtain $A = \Lambda_\delta^s(A) \cap sCl_\delta(A)$.

(3) \Rightarrow (1): Since $\Lambda_\delta^s(A)$ is a Λ_δ^s -set, $sCl_\delta(A)$ is δ -semiclosed and $A = \Lambda_\delta^s(A) \cap sCl_\delta(A)$. □

Proposition 3.3. *The following statements are true:*

- (1) Every Λ_δ^s -set (resp. δ -semiclosed set) is $(\Lambda, s\delta)$ -closed.
- (2) If A_i is $(\Lambda, s\delta)$ -closed for each $i \in I$, then $\bigcap\{A_i : i \in I\}$ is $(\Lambda, s\delta)$ -closed.

Proof. (1) It is obvious. (2) Suppose that A_i is $(\Lambda, s\delta)$ -closed for each $i \in I$. Then, for each $i \in I$ there exist a Λ_δ^s -set T_i and a semi- δ -closed set C_i such that $A_i = T_i \cap C_i$. Now

$$\begin{aligned} \bigcap\{A_i : i \in I\} &= \bigcap\{T_i \cap C_i : i \in I\} \\ &= \bigcap\{T_i : i \in I\} \cap \bigcap\{C_i : i \in I\} \end{aligned}$$

By Lemma 2.1, $\bigcap\{T_i : i \in I\}$ is a Λ_δ^s -set and $\bigcap\{C_i : i \in I\}$ is δ -semiclosed. This shows that $\bigcap\{A_i : i \in I\}$ is $(\Lambda, s\delta)$ -closed. □

Definition 4. A subset A of a space X is said to be $(s\delta, s\delta)$ -generalized closed if $sCl_\delta(A) \subseteq G$ holds whenever $A \subseteq G$ and $G \in \delta SO(X, \tau)$.

Proposition 3.4. *The following statements are true:*

- (1) *A subset A of a space X is $(s\delta, s\delta)$ -generalized closed if and only if $sCl_\delta(A) \subseteq \Lambda_\delta^s(A)$.*
- (2) *A subset A of a space X is δ -semiclosed if and only if A is $(s\delta, s\delta)$ -generalized closed and $(\Lambda, s\delta)$ -closed.*

Proof. (1) *Necessity.* Let $x \in X$ such that $x \notin \Lambda_\delta^s(A)$. So there exists a δ -semiopen subset O such that $A \subseteq O$ with $x \notin O$. This means that $x \notin sCl_\delta(A)$ since A is $(s\delta, s\delta)$ -generalized closed.

Sufficiency. Obvious.

(2) *Necessity.* Obvious

Sufficiency. Since A is $(s\delta, s\delta)$ -generalized closed, then $sCl_\delta(A) \subseteq \Lambda_\delta^s(A)$ (Proposition 3.4(1)). Now $A = \Lambda_\delta^s(A) \cap sCl_\delta(A) = sCl_\delta(A)$. \square

Definition 5. A subset A of a space X is called $(\Lambda, s\delta)$ -open if $X \setminus A$ is $(\Lambda, s\delta)$ -closed.

Proposition 3.5. *The following statements are true:*

- (1) *The union of any family of $(\Lambda, s\delta)$ -open sets is a $(\Lambda, s\delta)$ -open set.*
- (2) *Every Λ_δ^s -set is $(\Lambda, s\delta)$ -open.*

Proof. (1) The proof of this theorem follows by the fact that the intersection of a family of $(\Lambda, s\delta)$ -closed sets is $(\Lambda, s\delta)$ -closed (Proposition 3.3).

(2) Take $A = A \cup \emptyset$, where A is a Λ_δ^s -set, X is δ -semiclosed and $\emptyset = X \setminus X$. \square

Proposition 3.6. *The following statements are equivalent for a subset A of a space X :*

- (1) *A is $(\Lambda, s\delta)$ -open*
- (2) *$A = T \cup C$, where T is a Λ_δ^s -set and C is a δ -semiopen set.*

Proof. Straightforward. \square

Definition 6. Let X be a space and $A \subseteq X$. A point $x \in X$ is called $(\Lambda, s\delta)$ -cluster point of A if for every $(\Lambda, s\delta)$ -open set U of X containing x we have $A \cap U \neq \emptyset$. The set of all $(\Lambda, s\delta)$ -cluster points is called the $(\Lambda, s\delta)$ -closure of A and is denoted by $A^{(\Lambda, s\delta)}$.

Proposition 3.7. *Let A and B be subsets of a space X . Then, the following properties hold.*

- (1) $A \subset A^{(\Lambda, s\delta)}$.
- (2) $A^{(\Lambda, s\delta)} = \cap\{F \mid A \subset F \text{ and } F \text{ is } (\Lambda, s\delta)\text{-closed}\}$.
- (3) If $A \subset B$, then $A^{(\Lambda, s\delta)} \subset B^{(\Lambda, s\delta)}$.
- (4) A is $(\Lambda, s\delta)$ -closed if and only if $A = A^{(\Lambda, s\delta)}$.
- (5) $A^{(\Lambda, s\delta)}$ is $(\Lambda, s\delta)$ -closed.

Definition 7. A subset A of a space X is called a Λ_δ^s - D set if there are two $(\Lambda, s\delta)$ -open sets U and V in X such that $U \neq X$ and $A = U - V$.

Clearly every $(\Lambda, s\delta)$ -open set U different from X is a Λ_δ^s - D set.

Definition 8. A space X is called

- (1) Λ_δ^s - D_0 if for any distinct pair of points x and y of X there exists a Λ_δ^s - D set of X containing x but not y or a Λ_δ^s - D set of X containing y but not x .
- (2) Λ_δ^s - D_1 if for any distinct pair of points x and y of X there exist a Λ_δ^s - D set of X containing x but not y and a Λ_δ^s - D set of X containing y but not x .
- (3) Λ_δ^s - D_2 if for any distinct pair of points x and y of X there exist disjoint Λ_δ^s - D sets G and E of X containing x and y , respectively.

Example 3.8. Let (X, τ) be a space such that $X = \{a, b, c, d\}$ and $\tau = \{\emptyset, X, \{c\}, \{c, d\}, \{a, b\}, \{a, b, c\}\}$. Then

$$\delta SO(X, \tau) = \{\emptyset, X, \{a, b\}, \{c, d\}\}.$$

Also the family of all $(\Lambda, s\delta)$ -closed and the family of all Λ_δ^s - D sets is the family $\{\emptyset, X, \{a, b\}, \{c, d\}\}$. Clearly, the space (X, τ) is not Λ_δ^s - D_2 and it is not Λ_δ^s - D_1 .

Definition 9. A space X satisfies the $(\Lambda, s\delta)$ -property if for any distinct pair of points in X , there is a $(\Lambda, s\delta)$ -open set containing one of the points but not the other.

Proposition 3.9. *For a space X , the following statements are true:*

- (1) X is Λ_δ^s - D_0 if and only if it satisfies the $(\Lambda, s\delta)$ -property.
- (2) X is Λ_δ^s - D_1 if and only if it is Λ_δ^s - D_2 .

Proof. The sufficiency for (1) and (2) are obvious.

Necessity condition for (1). Let X be $\Lambda_\delta^s\text{-}D_0$ so that for any distinct pair of points x and y of X at least one belongs to a $\Lambda_\delta^s\text{-}D$ set O . Therefore we choose $x \in O$ and $y \notin O$. Suppose $O = U - V$ for which $U \neq X$ and U and V are $(\Lambda, s\delta)$ -open sets in X . This implies that $x \in U$. For the case that $y \notin O$ we have (i) $y \notin U$, (ii) $y \in U$ and $y \in V$. For (i), the space X satisfies the $(\Lambda, s\delta)$ -property since $x \in U$ and $y \notin U$. For (ii), the space X also satisfies the $(\Lambda, s\delta)$ -property since $y \in V$ but $x \notin V$.

Necessity condition for (2). Suppose that X is $\Lambda_\delta^s\text{-}D_1$. It follows from the definition that for any distinct points x and y in X there exist $\Lambda_\delta^s\text{-}D$ sets G and E such that G containing x but not y and E containing y but not x . Let $G = U - V$ and $E = W - D$, where U, V, W and D are $(\Lambda, s\delta)$ -open sets in X . By the fact that $x \notin E$, we have two cases, i.e. either $x \notin W$ or both W and D contain x . If $x \notin W$, then from $y \notin G$ either (i) $y \notin U$ or (ii) $y \in U$ and $y \in V$. If (i) is the case, then it follows from $x \in U - V$ that $x \in U - (V \cup W)$, and also it follows from $y \in W - D$ that $y \in W - (U \cup D)$. Thus we have $U - (V \cup W)$ and $W - (U \cup D)$ which are disjoint. If (ii) is the case, it follows that $x \in U - V$, $y \in V$ and $(U - V) \cap V = \emptyset$. If $x \in W$ and $x \in D$, we have $y \in W - D$, $x \in D$ and $(W - D) \cap D = \emptyset$. This shows that X is $\Lambda_\delta^s\text{-}D_2$. \square

Definition 10. Let X be a space. A point $x \in X$ which has only X as the $(\Lambda, s\delta)$ -neighborhood is called a $\Lambda_\delta^s\text{-neat}$ point.

Proposition 3.10. A space X which has the $(\Lambda, s\delta)$ -property is $\Lambda_\delta^s\text{-}D_1$ if and only if X has no $\Lambda_\delta^s\text{-neat}$ point.

Proof. (1) \Rightarrow (2). Since X is $\Lambda_\delta^s\text{-}D_1$, so each point x of X is contained in a $\Lambda_\delta^s\text{-}D$ set $O = U - V$ and thus in U . By definition $U \neq X$. This implies that x is not a $\Lambda_\delta^s\text{-neat}$ point.

(2) \Rightarrow (1). Since X satisfies the $(\Lambda, s\delta)$ -property, then for each distinct pair of points $x, y \in X$, at least one of them, choose x for example has a $(\Lambda, s\delta)$ -neighborhood U containing x and not y . Thus U which is different from X is a $\Lambda_\delta^s\text{-}D$ set. If X has no $\Lambda_\delta^s\text{-neat}$ point, then y is not a $\Lambda_\delta^s\text{-neat}$ point. This means that there exists a $(\Lambda, s\delta)$ -neighborhood V of y such that $V \neq X$. Thus $y \in (V - U)$ but not x and $V - U$ is a $\Lambda_\delta^s\text{-}D$ set. Hence X is $\Lambda_\delta^s\text{-}D_1$. \square

Remark 3.11. It is clear that a space X that satisfies the $(\Lambda, s\delta)$ -property is not Λ_δ^s - D_1 if and only if there is a unique Λ_δ^s -neat point in X . It is unique because if x and y are both Λ_δ^s -neat point in X , then at least one of them say x has a $(\Lambda, s\delta)$ -neighborhood U containing x but not y . But this is a contradiction since $U \neq X$.

Definition 11. A space X is called a $(\Lambda, s\delta)$ -symmetric if for x and y in X , $x \in y^{(\Lambda, s\delta)}$ implies $y \in x^{(\Lambda, s\delta)}$.

Proposition 3.12. A space X is $(\Lambda, s\delta)$ -symmetric if and only if for $x \in X$, $x^{(\Lambda, s\delta)} \subseteq E$ whenever $x \in E$ and E is $(\Lambda, s\delta)$ -open in X .

Proof. Assume that $x \in y^{(\Lambda, s\delta)}$ but $y \notin x^{(\Lambda, s\delta)}$. This means that the complement of $x^{(\Lambda, s\delta)}$ contains y . Therefore the set $\{y\}$ is a subset of the complement of $x^{(\Lambda, s\delta)}$. This implies that $y^{(\Lambda, s\delta)}$ is a subset of the complement of $x^{(\Lambda, s\delta)}$. Now the complement of $x^{(\Lambda, s\delta)}$ contains x which is a contradiction.

Conversely, suppose that $\{x\} \subset E$ and E is $(\Lambda, s\delta)$ -open in X but $x^{(\Lambda, s\delta)}$ is not a subset of E . This means that $x^{(\Lambda, s\delta)}$ and the complement of E are not disjoint. Let y belong to their intersection. Now we have $x \in y^{(\Lambda, s\delta)}$ which is a subset of the complement of E and $x \notin E$. But this is a contradiction. \square

Proposition 3.13. For a $(\Lambda, s\delta)$ -symmetric space X , the following are equivalent:

- (1) X is Λ_δ^s - D_0 .
- (2) X is Λ_δ^s - D_1 .

Proof. (2) \Rightarrow (1) : Proposition 3.9.

(1) \Rightarrow (2) : Since the space X is Λ_δ^s - D_0 by Proposition 3.9 satisfies the $(\Lambda, s\delta)$ -property. Let $x \neq y$. We may assume that $x \in E \subset \{y\}^c$ for some $(\Lambda, s\delta)$ -open set E in (X, τ) . Then $x \notin y^{(\Lambda, s\delta)}$ and hence $y \notin x^{(\Lambda, s\delta)}$. Hence there exists a $(\Lambda, s\delta)$ -open set F such that $y \in F \subset \{x\}^c$. Since every $(\Lambda, s\delta)$ -open set is a Λ_δ^s - D set, we have that (X, τ) is a Λ_δ^s - D_1 space. \square

4. $(\Lambda, s\delta)$ -CONTINUOUS FUNCTIONS

Definition 12. Let (X, τ) and (Y, σ) two spaces. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is called $(\Lambda, s\delta)$ -continuous if for each point $x \in X$ and every $(\Lambda, s\delta)$ -open set V of Y containing $f(x)$, there exists a $(\Lambda, s\delta)$ -open set U of X containing x such that $f(U) \subseteq V$.

We recall that a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be δ -semicontinuous [3] if $f^{-1}(V)$ is δ -semiopen in (X, τ) for each δ -semiopen set V of (Y, σ) .

Example 4.1. Let (X, τ) be as in Example 3.1. The function $f : (X, \tau) \rightarrow (X, \tau)$ for which $f(a) = c$, $f(b) = a$ and $f(c) = b$ is $(\Lambda, s\delta)$ -continuous, but f is not continuous and also is not δ -semicontinuous.

Definition 13. Let X be a space, $x \in X$ and $\{x_s, s \in S\}$ be a net of X . We say that the net $\{x_s, s \in S\}$ $(\Lambda, s\delta)$ -converges to x if for every $(\Lambda, s\delta)$ -open set U containing x there exists an element $s_0 \in S$ such that $s \geq s_0$ implies $x_s \in U$.

Proposition 4.2. Let X be a space and $A \subseteq X$. A point $x \in A^{(\Lambda, s\delta)}$ if and only if there exists a net $\{x_s, s \in S\}$ of A which $(\Lambda, s\delta)$ -converges to x .

Proof. The existence of such a net clearly implies that $x \in A^{(\Lambda, s\delta)}$. Let us suppose that $x \in A^{(\Lambda, s\delta)}$ and let us denote by \mathcal{U} the set of all $(\Lambda, s\delta)$ -open subsets U of X such that $x \in U$ directed by the relation \leq i.e., let us define that $U_1 \leq U_2$ if $U_2 \subseteq U_1$. Easily, the net $\{x_U, U \in \mathcal{U}\}$, where x_U is an arbitrary point of $A \cap U$, $(\Lambda, s\delta)$ -converges to x . \square

Proposition 4.3. For a function $f : (X, \tau) \rightarrow (Y, \sigma)$, the following are equivalent:

- (1) f is $(\Lambda, s\delta)$ -continuous.
- (2) $f^{-1}(V)$ is $(\Lambda, s\delta)$ -open in (X, τ) for every $(\Lambda, s\delta)$ -open set V of (Y, σ) .
- (3) $f^{-1}(F)$ is $(\Lambda, s\delta)$ -closed in (X, τ) for every $(\Lambda, s\delta)$ -closed set F of (Y, σ) .
- (4) $f(A^{(\Lambda, s\delta)}) \subset [f(A)]^{(\Lambda, s\delta)}$ for each subset A of X .
- (5) $[f^{-1}(B)]^{(\Lambda, s\delta)} \subset f^{-1}(B^{(\Lambda, s\delta)})$ for each subset B of Y .

(6) For every $x \in X$ and every net $\{x_s, s \in S\}$ of X which $(\Lambda, s\delta)$ -converges to x in X , the net $\{f(x_s), s \in S\}$ $(\Lambda, s\delta)$ -converges to $f(x)$ in Y .

Proof. (1) \Rightarrow (2): Let V be any $(\Lambda, s\delta)$ -open set of (Y, σ) and $x \in f^{-1}(V)$. Since f is $(\Lambda, s\delta)$ -continuous, there exists a $(\Lambda, s\delta)$ -open set U_x containing x such that $f(U_x) \subset V$. Therefore, we have $x \in U_x \subset f^{-1}(V)$ and hence $f^{-1}(V) = \cup\{U_x \mid x \in f^{-1}(V)\}$. By Proposition 3.5, $f^{-1}(V)$ is $(\Lambda, s\delta)$ -open in (X, τ) .

(2) \Rightarrow (1): This is obvious.

(2) \Leftrightarrow (3): This is obvious from Definition 5.

(3) \Rightarrow (4): Let A be any subset of X . Since $A \subset f^{-1}([f(A)]^{(\Lambda, s\delta)})$, by Proposition 3.7 we have $A^{(\Lambda, s\delta)} \subset f^{-1}([f(A)]^{(\Lambda, s\delta)})$ and hence $f(A^{(\Lambda, s\delta)}) \subset [f(A)]^{(\Lambda, s\delta)}$.

(4) \Rightarrow (5): Let B be any subset of Y . By (4) and Proposition 3.7, we have $f([f^{-1}(B)]^{(\Lambda, s\delta)}) \subset [f(f^{-1}(B))]^{(\Lambda, s\delta)} \subset B^{(\Lambda, s\delta)}$ and hence $[f^{-1}(B)]^{(\Lambda, s\delta)} \subset f^{-1}(B^{(\Lambda, s\delta)})$.

(5) \Rightarrow (3): Let F be any $(\Lambda, s\delta)$ -closed set in (Y, σ) . By Proposition 3.7,

$$[f^{-1}(F)]^{(\Lambda, s\delta)} \subset f^{-1}(F^{(\Lambda, s\delta)}) = f^{-1}(F)$$

and

$$[f^{-1}(F)]^{(\Lambda, s\delta)} \subset f^{-1}(F).$$

Therefore, we obtain $[f^{-1}(F)]^{(\Lambda, s\delta)} = f^{-1}(F)$. This shows that $f^{-1}(F)$ is $(\Lambda, s\delta)$ -closed in (X, τ) .

(1) \Rightarrow (6): Let $x \in X$ and $\{x_s \mid s \in S\}$ be a net $(\Lambda, s\delta)$ -converging to x . For any $(\Lambda, s\delta)$ -open set of (Y, σ) containing $f(x)$, by (1) there exists a $(\Lambda, s\delta)$ -open set U of X containing x such that $f(U) \subset V$. Since $\{x_s \mid s \in S\}$ converges to x , there exists $s_0 \in S$ such that $s \geq s_0$ implies $x_s \in U$. Therefore, $f(x_s) \in V$ for any $s \geq s_0$ and the net $\{f(x_s) \mid s \in S\}$ $(\Lambda, s\delta)$ -converges to $f(x)$.

(6) \Rightarrow (1): Let us suppose that there exists a point $x \in X$ and a $(\Lambda, s\delta)$ -open neighbourhood V of $f(x)$ such that for every $(\Lambda, s\delta)$ -open set U of X containing x such that $f(U) \not\subseteq V$. Then for every $(\Lambda, s\delta)$ -open set U of X such that $x \in U$, we choose an element $x_U \in U$ such that $f(x_U) \notin V$. Let \mathcal{U} be the set of all $(\Lambda, s\delta)$ -open sets U of X containing x , directed by the relation \subseteq i.e.,

let us define that $U_1 \leq U_2$ if $U_2 \subseteq U_1$. Observe that the net $\{x_U, U \in \mathcal{U}\}$ $(\Lambda, s\delta)$ -converges to x but the net $\{f(x_U), U \in \mathcal{U}\}$ does not $(\Lambda, s\delta)$ -converge to $f(x)$ which is a contradiction. Thus there exists a $(\Lambda, s\delta)$ -open set U of X such that $x \in U$ and $f(U) \subseteq V$. \square

Clearly, if a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is δ -semicontinuous, then $f : (X, \tau^{\Lambda_\delta^s *}) \rightarrow (Y, \sigma^{\Lambda_\delta^s *})$ is continuous.

Indeed let V be any $\Lambda_\delta^s *$ -set of (Y, σ) . Then

$$V = \Lambda_\delta^s *(V) = \cup\{W \mid V \supset W \in \delta SC(Y, \sigma)\}.$$

Since f is δ -semicontinuous, we have

$$\begin{aligned} f^{-1}(V) &= \cup\{f^{-1}(W) \mid f^{-1}(V) \supset f^{-1}(W) \in \delta SC(X, \tau)\} \\ &\subset \cup\{U \mid f^{-1}(V) \supset U \in \delta SC(X, \tau)\} \\ &= \Lambda_\delta^s *(f^{-1}(V)). \end{aligned}$$

On the other hand, by Lemma 2.3, we have $f^{-1}(V) \supset \Lambda_\delta^s *(f^{-1}(V))$ and hence $f^{-1}(V)$ is a $\Lambda_\delta^s *$ -set of (X, τ) . \square

By the above we have that if a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is δ -semicontinuous, then $f : (X, \tau^{\Lambda_\delta^s *}) \rightarrow (Y, \sigma^{\Lambda_\delta^s *})$ is continuous.

Proposition 4.4. *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a δ -semicontinuous function, then it is $(\Lambda, s\delta)$ -continuous.*

Proof. Let F be any $(\Lambda, s\delta)$ -closed set of (Y, σ) . Then there exist a Λ_δ^s -set T and a δ -semiclosed set D such that $F = T \cap D$. Since f is δ -continuous, $f^{-1}(D)$ is δ -semiclosed and $f^{-1}(T)$ is a Λ_δ^s -set of (X, τ) . Therefore, $f^{-1}(F) = f^{-1}(T) \cap f^{-1}(D)$ is a $(\Lambda, s\delta)$ -closed set of (X, τ) . By Proposition 4.3, f is $(\Lambda, s\delta)$ -continuous. \square

5. $(\Lambda, s\delta)$ -COMPACTNESS AND $(\Lambda, s\delta)$ -CONNECTEDNESS

Definition 14. A space X is called $(\Lambda, s\delta)$ -compact (resp. δ -semicompact) if every cover of X by $(\Lambda, s\delta)$ -open (resp. δ -semiopen) sets has a finite subcover.

Proposition 5.1. *A space X is $(\Lambda, s\delta)$ -compact (resp. δ -semicompact) if and only if for every family $\{A_i : i \in I\}$ of $(\Lambda, s\delta)$ -closed (resp. δ -semiclosed) sets in X satisfying $\cap\{A_i : i \in I\} = \emptyset$, there is a finite subfamily A_{i_1}, \dots, A_{i_n} with $\cap\{A_{i_k} : k = 1, \dots, n\} = \emptyset$.*

Proof. Straightforward. \square

Proposition 5.2. *For a space (X, τ) , the following hold:*

- (1) *If $(X, \tau^{\Lambda_\delta^s})$ is compact, then (X, τ) is δ -semicompact.*
- (2) *If (X, τ) is $(\Lambda, s\delta)$ -compact, then (X, τ) is δ -semicompact.*
- (3) *If (X, τ) is $(\Lambda, s\delta)$ -compact, then $(X, \tau^{\Lambda_\delta^{s*}})$ is compact.*

Proof. (1) Let $\{V_\alpha \mid \alpha \in \nabla\}$ be any δ -semiopen cover of X . By Lemma 2.1 V_α is a Λ_δ^s -set for each $\alpha \in \nabla$. Moreover, by the compactness of $(X, \tau^{\Lambda_\delta^s})$ there exists a finite subset ∇_0 of ∇ such that $X = \cup\{V_\alpha \mid \alpha \in \nabla_0\}$. This shows that (X, τ) is δ -semicompact.

(2) Let $\{F_\alpha \mid \alpha \in \nabla\}$ be a family of δ -semiopen sets of (X, τ) such that $\cap\{F_\alpha \mid \alpha \in \nabla\} = \emptyset$. Every δ -semiclosed set is $(\Lambda, s\delta)$ -closed set for each $\alpha \in \nabla$. By Proposition 5.1, there exists a finite subset ∇_0 of ∇ such that $\cap\{F_\alpha \mid \alpha \in \nabla_0\} = \emptyset$. Therefore (X, τ) is δ -semicompact.

(3) Let $\{V_\alpha \mid \alpha \in \nabla\}$ be a cover of X by Λ_δ^{s*} -sets of (X, τ) . Since $V_\alpha = V_\alpha \cup \emptyset$ and the empty set is δ -semiopen, by Lemma 2.1 each V_α is $(\Lambda, s\delta)$ -open in (X, τ) . Since (X, τ) is $(\Lambda, s\delta)$ -compact, there exists a finite subset ∇_0 of ∇ such that $X = \cup\{V_\alpha \mid \alpha \in \nabla_0\}$. This shows that $(X, \tau^{\Lambda_\delta^{s*}})$ is compact. \square

Proposition 5.3. *The following statements are true:*

- (1) *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a $(\Lambda, s\delta)$ -continuous surjection and (X, τ) is a $(\Lambda, s\delta)$ -compact space, then (Y, σ) is $(\Lambda, s\delta)$ -compact.*
- (2) *The $(\Lambda, s\delta)$ -compactness is preserved by δ -continuous surjections.*

Proof. (1) Let $\{V_i \mid i \in I\}$ be any cover of Y by $(\Lambda, s\delta)$ -open sets of (Y, σ) . Since f is $(\Lambda, s\delta)$ -continuous, by Proposition 4.3 $\{f^{-1}(V_i) \mid i \in I\}$ is a cover of X by $(\Lambda, s\delta)$ -open sets of (X, τ) . By $(\Lambda, s\delta)$ -compactness of (X, τ) , there exists a finite subset I_0 of I such that $X = \cup\{f^{-1}(V_i) \mid i \in I_0\}$. Since f is surjective, we obtain $Y = f(X) = \cup_{i \in I_0} V_i$. This shows that (Y, σ) is $(\Lambda, s\delta)$ -compact.

(2) This is an immediate consequence of (1) and Proposition 4.3. \square

Definition 15. A space X is called $(\Lambda, s\delta)$ -connected if X cannot be written as a disjoint union of two non-empty $(\Lambda, s\delta)$ -open sets.

Proposition 5.4. *For a space X , the following statements are equivalent:*

- (1) *The space X is $(\Lambda, s\delta)$ -connected.*
- (2) *The only subsets of X , which are both $(\Lambda, s\delta)$ -open and $(\Lambda, s\delta)$ -closed are the empty set \emptyset and X .*

Proof. Straightforward. □

Proposition 5.5. *The following statements are true:*

- (1) *A space (X, τ) is $(\Lambda, s\delta)$ -connected, then $(X, \tau^{\Lambda_\delta^s})$ is connected.*
- (2) *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a $(\Lambda, s\delta)$ -continuous surjection and (X, τ) is $(\Lambda, s\delta)$ -connected, then (Y, σ) is $(\Lambda, s\delta)$ -connected.*
- (3) *The $(\Lambda, s\delta)$ -connectedness is preserved by δ -continuous surjections.*

Proof. (1) Suppose that $(X, \tau^{\Lambda_\delta^s})$ is not connected. There exist nonempty Λ_δ^s -sets G, H of (X, τ) such that $G \cap H = \emptyset$ and $G \cup H = X$. By Proposition 3.3, G and H are $(\Lambda, s\delta)$ -closed sets. This shows that (X, τ) is not $(\Lambda, s\delta)$ -connected.

(2) Suppose that (Y, σ) is not $(\Lambda, s\delta)$ -connected. There exist nonempty $(\Lambda, s\delta)$ -open sets G, H of Y such that $G \cap H = \emptyset$ and $G \cup H = Y$. Then we have $f^{-1}(G) \cap f^{-1}(H) = \emptyset$ and $f^{-1}(G) \cup f^{-1}(H) = X$. Moreover, $f^{-1}(G)$ and $f^{-1}(H)$ are nonempty $(\Lambda, s\delta)$ -open sets of (X, τ) . This shows that (X, τ) is not $(\Lambda, s\delta)$ -connected. Therefore, (Y, σ) is $(\Lambda, s\delta)$ -connected.

(3) This is an immediate consequence of Proposition 4.3. □

6. SOME QUESTIONS

1. Does there exist a $(\Lambda, s\delta)$ -closed set which is not Λ_δ^s -set or δ -semiclosed?
2. Does there exist a non $(\Lambda, s\delta)$ -symmetric space which is Λ_δ^s - D_1 and it is not Λ_δ^s - D_0 ?
3. Does there exist a $(\Lambda, s\delta)$ -continuous function which is not δ -continuous?
4. Does there exist a δ -semicompact space (X, τ) such that the space $(X, \tau^{\Lambda_\delta^s})$ is not compact?

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